

Stochastic Galerkin method

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PANM 2020, June 2020

Outline

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 - Motivation.
 - The problem.
- 2 Stochastic Galerkin matrices.
- 3 Preconditioning of SGM matrices.
 - Numerical examples
 - More general connections

Motivation example.

Composite material with two material characteristics $\xi = (\xi_1, \xi_2)$.

We can solve:

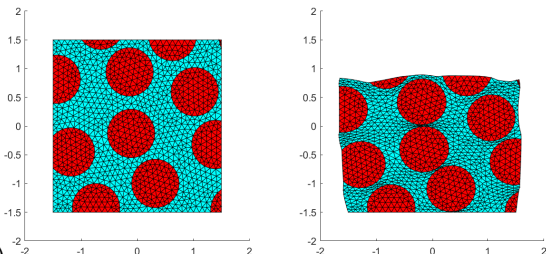
- dependence of displacements u on ξ for known distribution of ξ (for reliability determination),
- inverse problem - find ξ if u is given - images of original and loaded states are given (fig. by courtesy of L. Gaynutdinova)

Metropolis-Hastings algorithm:

For $k = 1, 2, \dots$

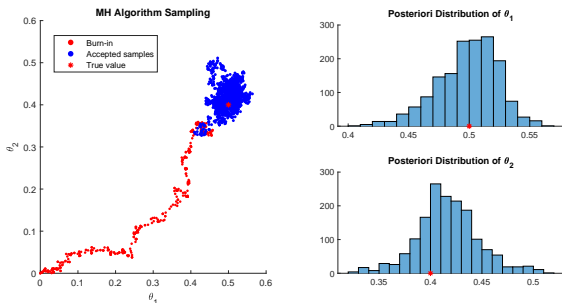
1. choose (random) parameters ξ^k
2. solve PDE with ξ^k
3. compare the error (between the solution and the goal) with the previous error
4. either accept ξ^k or accept the previous "successful" ξ^j

Post-processing: get probability distribution from the all accepted ξ 's.



Motivation example - cont.

(figures by courtesy of L. Gaynutdinova)



The PDE must be solved for many parameters ξ !

Better to get a *direct dependence* of the solution $u = u(x, \xi)$ on ξ ,

$$u(x, \xi) = \sum_{j=1}^{N_{\text{pol}}} \sum_{s=1}^{N_{\text{FE}}} u_{js} \psi_s(x) \phi_j(\xi)$$

(then no solution of PDE in MH algorithm).

The problem

Boundary value problem with random coefficient $a(x, \omega)$ (random field)

$$-\nabla \cdot a(x, \omega) \nabla u(x, \omega) = f(x) \quad \text{for } (x, \omega) \in D \times \Omega,$$

$u(x, \omega) = 0$ on $\partial D \times \Omega$, where (Ω, Σ, P) is a complete probability space.

Numerical computation: discrete finite random field,

Doob–Dynkin lemma: measure space $L^2_\rho(\Gamma)$, $\rho(\xi) = dP/d\xi$,

$$a(x, \omega) := a(x, \xi(\omega)), \quad \xi(\omega) = (\xi_1(\omega), \dots, \xi_{N_\xi}(\omega)),$$

where the random variables $\xi_i(\omega)$ are iid with the joint probability density

$$\rho(\xi) = \prod_{i=1}^{N_\xi} \rho_i(\xi_i) \quad \text{and} \quad \Gamma = \prod_{i=1}^{N_\xi} \Gamma_i = \prod_{i=1}^{N_\xi} \text{Im}(\xi_i).$$

R. Blaheta, M. Běreš, S. Domesová, P. Pan (Wuhan), A comparison of deterministic and Bayesian inverse with application in micromechanics, Applications of Mathematics, 2018

A. J. Crowder, Adaptive and Multilevel Stochastic Galerkin Finite Element Methods, Ph.D. Thesis, 2020

Methods:

- Monte Carlo solves

$$\int_D \mathbf{a}(x, \xi) \nabla u(x, \xi) \nabla v(x) dx = \int_D f(x) v(x) dx$$

+ non intrusive; Multilevel Monte Carlo

- large set of samples/problems; no exact error estimation

- Collocation method

+ non intrusive; sparse grids can be used

- non-nested sets of test samples for Gauss q. or nested for Clenshaw–Curtis q.

- Stochastic Galerkin method (SGM) solves (in a subspace of $L^2_\rho(\Gamma, H_0^1(D))$)

$$\int_\Gamma \int_D \mathbf{a}(x, \xi) \nabla u(x, \xi) \nabla v(x, \xi) \rho(\xi) dx d\xi = \int_\Gamma \int_D f(x) v(x, \xi) \rho(\xi) dx d\xi$$

+ error estimates available; the matrix is not constructed

- intrusive (but double-orthogonal polynomials); large matrices; coupled problems

Variational form of a deterministic problem with N_ξ parameters:

find $u \in V = H_0^1(D) \times L_p^2(\Gamma) = L_p^2(\Gamma, H_0^1(D))$ such that for any $v \in V$

$$\int_{\Gamma} \int_D \mathbf{a}(x, \xi) \nabla u(x, \xi) \nabla v(x, \xi) \rho(\xi) dx d\xi = \int_{\Gamma} \int_D f(x) v(x, \xi) \rho(\xi) dx d\xi,$$

where $\mathbf{a}(x, \xi)$ is defined

- on subdomains:

$$\mathbf{a}(x, \xi) = \sum_{k=1}^{N_\xi} \xi_k(\omega) \chi_{D_k}(x), \quad \text{subdomains } D_k,$$

- or by Karhunen-Loève expansion:

$$\mathbf{a}(x, \xi) = \mu(x) + \sum_{k=1}^{\infty} \xi_k(\omega) \sqrt{\lambda_k} a_k(x),$$

where ξ_k are uncorelated random variables with zero mean and unit variance, $a_k(x)$ are eigenfunctions of the covariance operator with

$$C(g)(x) = \int_D c(x, y) g(y) dy, \quad c(x, y) = \text{cov}(a(x, \omega), a(y, \omega)).$$

Two frequent forms of the coefficient function (discrete finite random field):

$$\int_{\Gamma} \int_D \mathbf{a}(x, \xi) \nabla u(x, \xi) \nabla v(x, \xi) \rho(\xi) dx d\xi = \int_{\Gamma} \int_D f(x) v(x, \xi) \rho(\xi) dx d\xi.$$

or

$$\int_{\Gamma} \int_D e^{\mathbf{a}(x, \xi)} \nabla u(x, \xi) \nabla v(x, \xi) \rho(\xi) dx d\xi = \int_{\Gamma} \int_D f(x) v(x, \xi) \rho(\xi) dx d\xi.$$

where $\mathbf{a}(x, \xi)$ is in the form (e.g. Karhunen-Loève expansion):

$$\mathbf{a}(x, \xi) \approx \mathbf{a}_0(x) + \sum_{i=1}^{N_{\xi}} \xi_i \mathbf{a}_i(x),$$

or

$$e^{\mathbf{a}(x, Y)} \approx e^{\mathbf{a}_0(x) + \sum_{i=1}^{N_{\xi}} \xi_i \mathbf{a}_i(x)} \approx \sum_{k=1}^m \Phi_k(\xi_1, \dots, \xi_{N_{\xi}}) \tilde{\mathbf{a}}_k(x),$$

$\Phi_k(\xi)$ are N_{ξ} -variate orthogonal polynomials:

Hermite polynomials for normal distribution $\rho(\xi) = \frac{1}{\sqrt{\pi}} e^{-\xi^2/2}$,

Legendre polynomials for uniform distribution $\rho(\xi) = \frac{1}{2} \chi_{(-1,1)}$,

etc.

Discretization of $u(x, \xi) \in H_0^1(D) \times L^2_\rho(\Gamma)$:

FE basis and generalized polynomial chaos expansion (PCE) of the solution:

$$u(x, \xi) = \sum_{j=1}^{N_{\text{pol}}} \sum_{r=1}^{N_{\text{FE}}} u_{jr} \psi_r(x) \phi_j(\xi),$$

FE basis $\{\psi_r(x)\}_{r=1}^{N_{\text{FE}}}$

N_ξ -variate orthogonal polynomials $\{\phi_j(\xi)\}_{j=1}^{N_{\text{pol}}}$, $\phi_j(\xi) = \phi_{j,1}(\xi_1) \dots \phi_{j,N_\xi}(\xi_{N_\xi})$

complete polynomials (CP) of total order $\leq P$,

$$N_{\text{pol}} = \binom{N_\xi + P}{N_\xi}$$

tensor products (TP) pol. of orders P_k in ξ_k , $k = 1, \dots, N_\xi$,

$$N_{\text{pol}} = \prod_{k=1}^{N_\xi} (P_k + 1)$$

$N_{\text{pol}} \times N_{\text{FE}}$ basis functions $\psi_r(x) \phi_j(\xi)$

unknowns u_{jr}

Regularity and a priori convergence estimates [I. Babuska, F. Nobile, R. Tempone, R. Ghanem, G.E. Zouraris, C.J. Gittelsohn, ...]

Matrix A and right hand side b :

$$A_{jr, is} = \int_{\Gamma} \int_D \left(a_0(x) + \sum_{k=1}^{N_{\xi}} \xi_k a_k(x) \right) \nabla \psi_s(x) \nabla \psi_r(x) \Phi_i(\xi) \Phi_j(\xi) \rho(\xi) dx d\xi$$

or

$$A_{jr, is} = \int_{\Gamma} \int_D \sum_{k=1}^m \Phi_k(\xi) \tilde{a}_k(x) \nabla \psi_s(x) \nabla \psi_r(x) \Phi_i(\xi) \Phi_j(\xi) \rho(\xi) dx d\xi$$

$$b_{jr} = \int_{\Gamma} \int_D f(x) \psi_r(x) \Phi_j(\xi) \rho(\xi) dx d\xi$$

Example of uniform $a(x, \xi) = a_0(x) + \xi_1 a_1(x) + \xi_2 a_2(x)$:

$N_\xi = 2$, $P = 2$, uniform distribution, Legendre approximation polynomials, CP:

$$A = \left(\begin{array}{ccc|ccc} K_0 & \frac{1}{\sqrt{3}} K_1 & \frac{1}{\sqrt{3}} K_2 & 0 & 0 & 0 \\ \frac{1}{\sqrt{3}} K_1 & K_0 & 0 & \frac{2}{\sqrt{15}} K_1 & \frac{1}{\sqrt{3}} K_2 & 0 \\ \frac{1}{\sqrt{3}} K_2 & 0 & K_0 & 0 & \frac{1}{\sqrt{3}} K_1 & \frac{2}{\sqrt{15}} K_2 \\ \hline 0 & \frac{2}{\sqrt{15}} K_1 & 0 & K_0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{3}} K_2 & \frac{1}{\sqrt{3}} K_1 & 0 & K_0 & 0 \\ 0 & 0 & \frac{2}{\sqrt{15}} K_2 & 0 & 0 & K_0 \end{array} \right),$$

where K_0 , K_1 , and K_2 are the "stiffness matrices" corresponding to $a_0(x)$, $a_1(x)$, and $a_2(x)$, respectively,

$$(K_i)_{rs} = \int_D a_i(x) \nabla \psi_r(x) \nabla \psi_s(x) dx$$

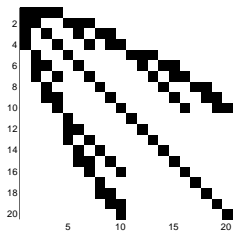
$$(G_i)_{jk} = \int_\Gamma \xi_i \Phi_j(\xi) \Phi_k(\xi) \rho(\xi) d\xi$$

$$(G_0)_{jk} = \int_\Gamma \Phi_j(\xi) \Phi_k(\xi) \rho(\xi) d\xi = \delta_{jk}$$

Jacobi matrices G_i

A is a sum of Kronecker products (which is never built):

$$A = \sum_{i=0}^2 G_i \otimes K_i$$

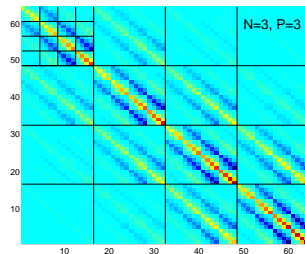
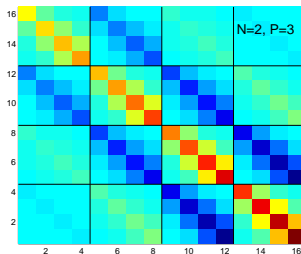


Example of exponential $a(x, \xi)$: A is a sum of Kronecker products:

$$\begin{aligned} A_{ir, js} &= \int_{\Gamma} \int_D \sum_{k=1}^m \Phi_k(\xi) \tilde{a}_k(x) \nabla \psi_s(x) \nabla \psi_r(x) \Phi_i(\xi) \Phi_j(\xi) \rho(\xi) dx d\xi \\ &= \sum_{k=1}^m \int_D \tilde{a}_k(x) \nabla \psi_s(x) \nabla \psi_r(x) dx \int_{\Gamma} \Phi_k(\xi) \Phi_i(\xi) \Phi_j(\xi) \rho(\xi) d\xi \\ &= \sum_{k=1}^m (K_k)_{rs} (G_{k,1})_{ij} \cdots (G_{k,N})_{ij} \end{aligned}$$

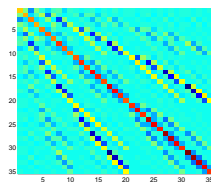
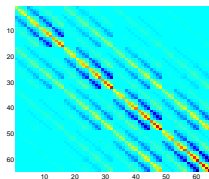
$$(G_{k,t})_{ij} = \int_{\mathcal{X}} \phi_{k,t}(\xi_t) \phi_{i,t}(\xi_t) \phi_{j,t}(\xi_t) \rho(\xi_t) d\xi_t$$

ordering of blocks
for TP



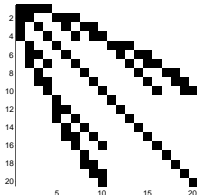
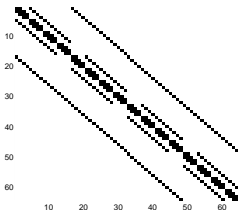
Log-normal $a(x, \xi)$

→ **dense** matrix A :



linear $a(x, \xi)$

→ **sparse** matrix A :



approximation of $u(x, \xi)$:

tensor product of polynomials in ξ_j (left), complete polynomials in ξ_j (right)

Low rank approximations: vector $u \rightarrow$ tensorised matrix U , and

$$v = Au = \left(\sum_{i=0}^{N_{\xi}} G_i \otimes K_i \right) u \quad \text{is the same as} \quad V = \sum_{i=0}^{N_{\xi}} K_i U G_i^T$$

C. Powell, D. Silvester, V. Simoncini, 2016; H. Matthies et al., 2014

Preconditioning of A :

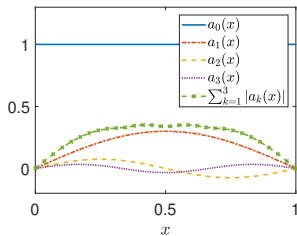
- with respect to spatial variables:
 - ”multigrid people” - M. Brezina, et al., 2014, H. Elman, D. Furnival, 2007
- with respect to stochastic variables:
 - only diagonal blocks - C. Powell, H. Elman, 2009
 - Kronecker product preconditioner - E. Ullmann, 2010
 - a posteriori error estimates - A. Bespalov, C. Powell, D. Silvester, 2014
 - two-by-two blocks and Schur complement - B. Sousedik, R. Ghanem, E. Phipps, 2013, (numerical tests)
- **now**: improved theoretical bounds for the condition number of preconditioned A

Example. $D = (0, 1)$, $N_\xi = 3$, $a(x, \xi) = a_0(x) + \xi_1 a_1(x) + \xi_2 a_2(x) + \xi_3 a_3(x)$,

$$-(a(x, \xi)u(x, \xi))' = f(x),$$

$\xi_i \in [-1, 1]$, $i = 1, 2, 3$.

Problem 1:



Problem 2:

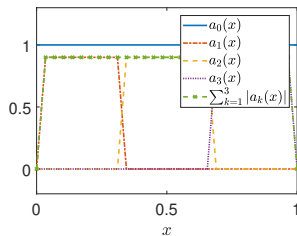


Table: Block-diagonal preconditioning of Problem 1 and Problem 2. New and classical bounds.

$P-1$	$\kappa(A)$	$\underline{c}_{\text{class}}$	\underline{c}	$\lambda_{\min}(M^{-1}A)$	$\lambda_{\max}(M^{-1}A)$	\bar{c}	\bar{c}_{class}	\bar{c}/\underline{c}
Problem 1								
1	458.42	0.76	0.80	0.83	1.17	1.20	1.24	1.51
2	498.47	0.68	0.73	0.76	1.24	1.27	1.32	1.75
...								
6	546.55	0.61	0.67	0.69	1.31	1.33	1.39	2.26
7	550.80	0.61	0.66	0.68	1.32	1.34	1.39	2.29
Problem 2								
1	947.79	-0.65	0.45	0.45	1.56	1.56	2.65	3.43
2	1596.34	-1.21	0.26	0.26	1.74	1.74	3.21	6.57
...								
6	4576.93	-1.71	0.10	0.10	1.90	1.90	3.71	19.34
7	5294.63	-1.74	0.09	0.09	1.91	1.91	3.74	21.80

I.P. AM 2015; I.P. CAMWA 2016; I.P. IJUQ 2017; M. Kubínová, I.P. SIAM/ASA JUQ 2020

Preconditioning of A - estimates of the condition number of $M^{-1}A$ - the main trick:

If

$$c_1 v^T M v \leq v^T A v \leq c_2 v^T M v$$

then

$$\kappa(M^{-1}A) \leq \frac{c_2}{c_1}.$$

At the same time,

$$v^T A v = \sum_{j=1}^n \int_{E_j} a(x, \xi) \nabla v(x) \cdot \nabla v(x) dx, \quad v^T M v = \sum_{j=1}^n \int_{E_j} \tilde{a}(x, \xi) \nabla v(x) \cdot \nabla v(x) dx,$$

thus c_1 and c_2 can be estimated locally !

$$c_1 \tilde{a}(x, \xi) \leq a(x, \xi) \leq c_2 \tilde{a}(x, \xi), \quad x \in E_j, \quad j = 1, \dots, n_E.$$

This approach can be used for FEM, stochastic Galerkin, hierarchical bases (AML), ..., for any type of symmetric matrices that are composed "element-wise".

Conclusion

- PDE with (stochastic) parameters - many methods, but all demanding
- Variational approach - stochastic Galerkin method
- Preconditioning - spectral estimates based on **local properties** of the original and preconditioning operators - joint approach for :
 - condition number estimates for AML preconditioning, **V. Eijkhout, P. Vassilevski, O. Axelsson**
 - condition number estimates for preconditioned stochastic Galerkin matrices
 - estimates of **all eigenvalues** of preconditioned matrices:
T. Gergelits, K.-A. Mardal, B. Nielsen and Z. Strakoš, SINUM 2019,
T. Gergelits, B. Nielsen, Z. Strakoš, SINUM 2020,
M. Ladecký, I. P., J. Zeman, AM 2020